

Theoretical aspects of scheduling coupled-tasks in the presence of compatibility graph

G. Simonin, B. Darties et R. Giroudeau

Volume 7, numéro 1, spring 2012

URI : https://id.erudit.org/iderudit/aor7_1art01

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Éditeur(s)

Preeminent Academic Facets Inc.

ISSN

1718-3235 (numérique)

[Découvrir la revue](#)

Citer cet article

Simonin, G., Darties, B. & Giroudeau, R. (2012). Theoretical aspects of scheduling coupled-tasks in the presence of compatibility graph. *Algorithmic Operations Research*, 7(1), 1–12.

Résumé de l'article

This paper presents a generalization of the coupled-task scheduling problem introduced by Shapiro [12], where considered tasks are subject to incompatibility constraints depicted by an undirected graph. The motivation of this problem comes from data acquisition and processing in a mono-processor torpedo used for underwater exploration. As we add the compatibility graph, we focus on complexity of the problem, and more precisely on the boundary between P and NP-completeness when some other input parameters are restricted (e.g. the ratio between the durations of the two sub-tasks composing a task): we adapt the global visualization of the complexity of scheduling problems with coupled-task given by Orman and Potts [11] to our model, determine new complexity results, and thus propose a new visualization including incompatibility constraints. In the end, we give a new polynomial-time approximation algorithm result which completes previous works.



Rodolphe GIROUDEAU

Dear Referees,

Please find below, an article entitled "Theoretical aspects of scheduling coupled-tasks in the presence of compatibility graph".

The corresponding author is Giroudeau Rodolphe : rgirou@lirmm.fr and postal address is

Giroudeau Rodolphe
LIRMM - UMR 5506 - CC 477
161 rue Ada
34095 Montpellier Cedex 5 - France

Best regards,

Rodolphe Giroudeau